LSP-LRD-01204 Laser Range Finder Module

Technical Specification



1. General

LSP-LRD-01204 semiconductor laser rangefinder is an innovative product that integrates advanced technology and humanized design carefully developed. Using a unique 905nm laser diode as the core light source, this model not only ensures human eye safety, but also sets a new benchmark in the field of laser ranging with its efficient energy conversion and stable output characteristics. Equipped with high-performance chips and advanced algorithms independently, the LSP-LRD-01204 achieves excellent performance with long life and low power consumption, perfectly meeting the market demand for high-precision and portable ranging equipment.

2. Main application

Used in UAV, sighting, outdoor handheld products and other ranging applications (aviation, police, railway, electricity, water conservancy, communication, environment, geology, construction, fire station, blasting, agriculture, forestry, outdoor sports, etc.)

3. Features

 High precision ranging data compensation algorithm: optimization algorithm, fine calibration

LSP-LRD-01204 semiconductor laser rangefinder, in pursuit of the ultimate accuracy of the road, innovatively adopted the advanced range data compensation algorithm, the algorithm through the combination of complex mathematical model and measured data, to generate accurate linear compensation curve. This technical breakthrough enables the rangefinder to carry out real-time and accurate correction of errors in the ranging process under various environmental conditions, so as to achieve the excellent performance of the full range accuracy control within 1 meter, and the short-range ranging accuracy is accurate to 0.1 meters.

Optimized ranging method: accurate measurement, improve ranging accuracy

The laser rangefinder adopts the high repetition frequency ranging method, through the continuous transmission of multiple laser pulses, and the accumulation and processing of the echo signal, so as to effectively suppress the noise and interference, and improve the signal to noise ratio. By optimizing the optical path design and signal processing algorithm, the stability and accuracy of the measurement results are ensured. This method can achieve accurate measurement of the target distance, even in the face of complex environments or small changes, but also to ensure the accuracy and stability of the measurement results.

Low power consumption design: Efficient energy saving and optimized performance

With the ultimate energy efficiency management as the core, this technology significantly reduces the energy consumption of the overall system without affecting the distance and accuracy by finely regulating the power consumption of key components such as the main control board, the drive board, the laser and the receiving amplifier board. This low-power design not only reflects the commitment to environmental protection, but also greatly improves the economy and sustainability of the equipment, becoming an important milestone in promoting the green development of ranging technology.

Working capacity under extreme conditions: excellent heat dissipation, guaranteed performance

LSP-LRD-01204 laser rangefinder with its excellent thermal design and stable manufacturing process, showing extraordinary performance under extreme working conditions. While ensuring high precision ranging and long range detection, the product can withstand extreme operating ambient temperatures of up to 65 $^{\circ}$ C, demonstrating its high reliability and durability in harsh environments.

Miniaturized design, no burden to carry

The LSP-LRD-01204 laser rangefinder uses an advanced miniaturization design

concept, which highly integrates the precision optical system and electronic components in a lightweight body weighing only 11 grams. This design not only greatly improves the portability of the product, allowing users to easily carry it around in a pocket or bag, but also makes it more flexible and convenient to use in complex outdoor environments or confined Spaces.

4. Technical parameter

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|-----------------------------|---------------------------|
| Item | Parameter |
| Wavelength | 905nm±5nm |
| Ranging capacity | 3~1500m (Building) |
| ranging capacity | ≥200m (target @0.6m×0.6m) |
| | ±0.1m (≤10m) |
| Ranging accuracy | ±0.5m (≤200m) |
| | ±1m (>200m) |
| Resolution | 0.1m |
| Ranging frequency | 1~4Hz |
| Accurate ratio | ≥98% |
| Beam divergency | ≤6mrad |
| Power supply | DC2.7V~5.0V |
| Operating power consumption | ≤1.5W |
| Standby power consumption | ≤0.8W |
| Sleep power consumption | ≤1mW |
| Communication type | UART (TTL_3.3V) |
| Baud rate | 115200/9600 |
| Dimension | 25×26×13mm |
| Weight | 11g+0.5g |
| Operating temperature | -40~+ 65℃ |
| Storage temperature | -45~+70°C |

| False alarm rate | ≤1% |
|------------------|-------------------------------|
| Impact | 1000g,1ms |
| Vibration | 5~50~5Hz, 1 octave /min, 2.5g |
| Start-up time | ≤200ms |

Note:

- Visibility ≥10km, humidity ≤70%
- Large target: the target size is greater than the spot size

5. Interface

Communication interface: UART(TTL_3.3V),115200bps.

Electrical interface: The interface model is FWF08002-S06B13W5M. See the following table for the interface definition.

6-pin connection definition

| No | Pin | Color | Remarks |
|----|----------|--------|---|
| 1 | GND | Green | Power input -/ Serial port |
| 2 | VIN+ | Yellow | Power input +(DC2.7V~5.0V) |
| 3 | NC | Orange | Vacant |
| 4 | UART_TX | Red | TTL serial port transmitter, 3.3V level |
| 5 | UART_RX | Brown | TTL serial port receiver, 3.3V level |
| | | | Module power supply is enabled, |
| 6 | POWER_EN | Black | TTL_3.3V level; Module on (>2.5V or |
| | | | suspended), module off (<0.3V); |

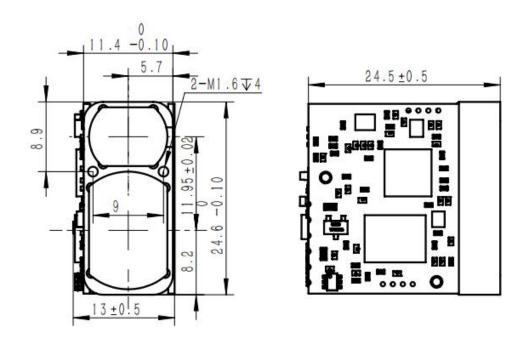
Sequence description: The serial number of the terminal pins of the interface is 1 to 6 from top to bottom.

6. Safety & notifications

- The laser emitted by this rangefinder module is a 905nm laser that is safe for human eyes, but it is recommended not to look directly at the laser.
- This measuring module is non-airtight, and must ensure that the relative

- humidity of the use environment is less than 70%, and ensure that the use of the environment is clean and sanitary, so as not to damage the laser.
- The range measurement of the range module is related to the atmospheric visibility and the nature of the target, and the range measurement will be reduced in the case of fog, rain and wind sand. Green leaf clusters, white walls, exposed limestone and other targets have better reflectivity, which can increase the measurement range. In addition, when the Angle of the target to the laser beam increases, the measurement range will be reduced.
- Do not plug and unplug the cable in the energized state; Ensure that the power supply polarity is correctly connected; otherwise, the device will be permanently damaged.
- After the ranging module is powered on, there are high-pressure and heating components on the circuit board. Do not touch the circuit board with your hands when the ranging module is working.

7. Layout dimension



LSP-LRD-01204 LRF Layout Drawing

8. Communication protocol

Laser ranging module adopts serial communication mode, the default baud rate is 115200bps.

Data format: eight bits of data, one start bit, one stop bit, no parity check. The data consists of header bytes, command part, data length, parameter part, and check bytes.

Communication mode: master and rangefinder adopt the master-slave communication mode, the master sends the control command to the rangefinder, and the rangefinder receives and executes the command. The range finder sends back the data and status of the range finder according to the range finder period, and the communication format and command content are shown in the following table.

a) Master transmitting

The format of the sent message is as follows:

| STX0 CMD LEN DATA1H DATA1L CHK |
|--------------------------------|
|--------------------------------|

Table 2 Description of the format of the sent packet

| No | Name | Instruction | Code | Remarks |
|----|-------|-----------------------|--|---------|
| 1 | STX0 | Start of message sent | 55(H) | |
| 2 | CMD | Command word | See Table 3 | |
| 3 | LEN | Data length | Refers to the length of the parameter | |
| 4 | DATAH | Parameter | See Table 3 | |
| 5 | DATAL | | | |
| 6 | СНК | Xor check | Except for the validation byte, other bytes are either | |

The command description is as follows:

Table 3 Command and data word description sent by the master to the rangefinder

| No. | Command | Function | Data byte | Remarks | Length | Sample code |
|-----|---------|---------------------------------|---------------------------|---|---------|---|
| 1 | 0×00 | Standby (continuous range stop) | 00 00 | Rangefinder stopped working | 6 bytes | 55 00 02 00 00 57 |
| 2 | 0x01 | Single ranging | 20 00 | 20 indicates the start working status | 6 bytes | 55 01 02 20 00 76 |
| 3 | 0x02 | Continuous ranging | 20 00 | 20 indicates the start working status | 6 bytes | 55 02 02 20 00 75 |
| 4 | 0x03 | self-inspection | 00 00 | | 6 bytes | 55 03 02 00 00 54 |
| 5 | 0x07 | High voltage reference setting | DATAH=XX (H) DATAL=YY (L) | Factory instruction; DATA Indicates voltage value *10, unit V | 6 bytes | 55 07 02 05 AA FF (Voltage 1450) |
| 6 | OxEB | Query version number | 00 00 | Factory order | 6 bytes | 55 CB 02 00 00 9C |

b) Master receive format

The format of the received message is as follows:

| STXO CMD LEN DATAN DATAO CHK |
|------------------------------|
|------------------------------|

Table 4 Format description of the received packet

| No | Name | Instruction | Code | Remarks |
|----|--------|----------------------|--|---------|
| 1 | STX0 | Message start flag | 55(H) | |
| 2 | CMD_JG | Data command word | See table 5 | |
| 3 | LEN | Data length | Indicates length of the parameter | |
| 4 | Dn | Parameter | See table 5 | |
| 5 | D0 | Parameter | | |
| 6 | СНК | Xor check | Except for the validation byte, other bytes are either | |

Master receiving status description:

Table 5 Description of data words sent by the range finder to the master $\,$

| No Command | Command Function | Data | Remarks | Total | |
|------------|------------------|----------------|---------|------------------------------|----------|
| NO | Commana | Function | byte | Remarks | length |
| | | Standby | | | 6 bytes |
| 1 | 0x00 | (continuous | 00 00 | Same request frame | |
| | | range stop) | | | |
| | | Single ranging | | D6 flag byte (not parsed for | 11 bytes |
| | | | | internal test use) : | |
| | | | D6 D5 | 0x20 indicates distant order | |
| | | | D4 D3 | 1, no previous target; | |
| 2 | 0x01 | | D2 D1 | 0x28 indicates distant order | |
| | | | D0 | 1, with a previous target; | |
| | | | | 0x30 indicates distant 2nd | |
| | | | | order, no previous target; | |
| | | | | 0x38 indicates distant order | |

| No | Command | Function | Data byte | Remarks | Total length |
|----|---------|--------------------|----------------|---|-----------------|
| | | | | 2, with a previous target D5-D3 Target distance (distance value divided by 10, unit 0.1m) D1 APD High voltage (unit: 1V) D0 APD temperature (unit: 1°C) | |
| 3 | 0x02 | Continuous ranging | D3 D2 D1 D0 | D6 flag byte (not parsed for internal test use): 0x20 indicates distant order 1, no previous target; 0x28 indicates distant order 1, with a previous target; 0x30 indicates distant 2nd order, no previous target; 0x38 indicates distant order 2, with a previous target D5-D3 Target distance (distance value divided by 10, unit 0.1m) D1 APD High voltage (unit: 1V) D0 APD temperature (unit: 1°C) | 11 bytes |
| 4 | 0x03 | self-inspection | D7 ~D0 | D6: APD high voltage reference value, unit 1V. D5-4: indicates the value of the blind area (unit: 1m) | 12 bytes |

| No | Command | Function | Data byte | Remarks | Total length |
|----|---------|--------------------------------|--------------|--|-----------------|
| | | | | D3: APD high pressure value after temperature compensation, unit 1V; D2: APD temperature (unit: 1°C); | |
| 5 | 0x07 | High voltage reference setting | D1~D0 | D1: High voltage value of the APD after temperature compensation D0: indicates the low voltage value of the APD after temperature compensation | 6 bytes |

Note: $\ \, \textcircled{1}\ \,$ No data bytes/bits are defined. The default value is 0